

NAG C Library Function Document

nag_zhseqr (f08psc)

1 Purpose

nag_zhseqr (f08psc) computes all the eigenvalues, and optionally the Schur factorization, of a complex Hessenberg matrix or a complex general matrix which has been reduced to Hessenberg form.

2 Specification

```
void nag_zhseqr (Nag_OrderType order, Nag_JobType job, Nag_ComputeZType compz,
                Integer n, Integer ilo, Integer ihi, Complex h[], Integer pdh, Complex w[],
                Complex z[], Integer pdz, NagError *fail)
```

3 Description

nag_zhseqr (f08psc) computes all the eigenvalues, and optionally the Schur factorization, of a complex upper Hessenberg matrix H :

$$H = ZTZ^H,$$

where T is an upper triangular matrix (the Schur form of H), and Z is the unitary matrix whose columns are the Schur vectors z_i . The diagonal elements of T are the eigenvalues of H .

The function may also be used to compute the Schur factorization of a complex general matrix A which has been reduced to upper Hessenberg form H :

$$\begin{aligned} A &= QHQ^H, \text{ where } Q \text{ is unitary,} \\ &= (QZ)T(QZ)^H. \end{aligned}$$

In this case, after nag_zgghrd (f08nsc) has been called to reduce A to Hessenberg form, nag_zunghr (f08ntc) must be called to form Q explicitly; Q is then passed to nag_zhseqr (f08psc), which must be called with **compz** = **Nag_UpdateZ**.

The function can also take advantage of a previous call to nag_zgebal (f08nvc) which may have balanced the original matrix before reducing it to Hessenberg form, so that the Hessenberg matrix H has the structure:

$$\begin{pmatrix} H_{11} & H_{12} & H_{13} \\ & H_{22} & H_{23} \\ & & H_{33} \end{pmatrix}$$

where H_{11} and H_{33} are upper triangular. If so, only the central diagonal block H_{22} (in rows and columns i_{lo} to i_{hi}) needs to be further reduced to Schur form (the blocks H_{12} and H_{23} are also affected). Therefore the values of i_{lo} and i_{hi} can be supplied to nag_zhseqr (f08psc) directly. Also, nag_zgebak (f08nwc) must be called after this function to permute the Schur vectors of the balanced matrix to those of the original matrix. If nag_zgebal (f08nvc) has not been called however, then i_{lo} must be set to 1 and i_{hi} to n . Note that if the Schur factorization of A is required, nag_zgebal (f08nvc) must **not** be called with **job** = **Nag_Schur** or **Nag_DoBoth**, because the balancing transformation is not unitary.

nag_zhseqr (f08psc) uses a multishift form of the upper Hessenberg QR algorithm, due to Bai and Demmel (1989). The Schur vectors are normalized so that $\|z_i\|_2 = 1$, but are determined only to within a complex factor of absolute value 1.

4 References

Bai Z and Demmel J W (1989) On a block implementation of Hessenberg multishift QR iteration *Internat. J. High Speed Comput.* **1** 97–112

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

- 1: **order** – Nag_OrderType *Input*
On entry: the **order** parameter specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order = Nag_RowMajor**. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this parameter.
Constraint: **order = Nag_RowMajor** or **Nag_ColMajor**.
- 2: **job** – Nag_JobType *Input*
On entry: indicates whether eigenvalues only or the Schur form T is required, as follows:
 if **job = Nag_EigVals**, eigenvalues only are required;
 if **job = Nag_Schur**, the Schur form T is required.
Constraint: **job = Nag_EigVals** or **Nag_Schur**.
- 3: **compz** – Nag_ComputeZType *Input*
On entry: indicates whether the Schur vectors are to be computed as follows:
 if **compz = Nag_NotZ**, no Schur vectors are computed (and the array \mathbf{z} is not referenced);
 if **compz = Nag_InitZ**, the Schur vectors of H are computed (and the array \mathbf{z} is initialised by the routine);
 if **compz = Nag_UpdateZ**, the Schur vectors of A are computed (and the array \mathbf{z} must contain the matrix Q on entry).
Constraint: **compz = Nag_NotZ, Nag_InitZ** or **Nag_UpdateZ**.
- 4: **n** – Integer *Input*
On entry: n , the order of the matrix H .
Constraint: $\mathbf{n} \geq 0$.
- 5: **ilo** – Integer *Input*
 6: **ihi** – Integer *Input*
On entry: if the matrix A has been balanced by nag_zgebal (f08nvc), then **ilo** and **ihi** must contain the values returned by that function. Otherwise, **ilo** must be set to 1 and **ihi** to \mathbf{n} .
Constraint: $\mathbf{ilo} \geq 1$ and $\min(\mathbf{ilo}, \mathbf{n}) \leq \mathbf{ihi} \leq \mathbf{n}$.
- 7: **h[*dim*]** – Complex *Input/Output*
Note: the dimension, dim , of the array \mathbf{h} must be at least $\max(1, \mathbf{pdh} \times \mathbf{n})$.
 If **order = Nag_ColMajor**, the (i, j) th element of the matrix H is stored in $\mathbf{h}[(j-1) \times \mathbf{pdh} + i - 1]$ and if **order = Nag_RowMajor**, the (i, j) th element of the matrix H is stored in $\mathbf{h}[(i-1) \times \mathbf{pdh} + j - 1]$.
On entry: the n by n upper Hessenberg matrix H , as returned by nag_zgehrd (f08nsc).
On exit: if **job = Nag_EigVals**, the array contains no useful information. If **job = Nag_Schur**, H is overwritten by the upper triangular matrix T from the Schur decomposition (the Schur form) unless **fail** > 0.

- 8: **pdh** – Integer *Input*
On entry: the stride separating matrix row or column elements (depending on the value of **order**) in the array **h**.
Constraint: **pdh** \geq $\max(1, \mathbf{n})$.
- 9: **w**[*dim*] – Complex *Output*
Note: the dimension, *dim*, of the array **w** must be at least $\max(1, \mathbf{n})$.
On exit: the computed eigenvalues, unless **fail** $>$ 0 (in which case see Section 6). The eigenvalues are stored in the same order as on the diagonal of the Schur form *T* (if computed).
- 10: **z**[*dim*] – Complex *Input/Output*
Note: the dimension, *dim*, of the array **z** must be at least
 $\max(1, \mathbf{pdz} \times \mathbf{n})$ when **compz** = **Nag_UpdateZ** or **Nag_InitZ**;
 1 when **compz** = **Nag_NotZ**.
 If **order** = **Nag_ColMajor**, the (*i*, *j*)th element of the matrix *Z* is stored in **z**[(*j* – 1) \times **pdz** + *i* – 1] and if **order** = **Nag_RowMajor**, the (*i*, *j*)th element of the matrix *Z* is stored in **z**[(*i* – 1) \times **pdz** + *j* – 1].
On entry: if **compz** = **Nag_UpdateZ**, **z** must contain the unitary matrix *Q* from the reduction to Hessenberg form; if **compz** = **Nag_InitZ**, **z** need not be set.
On exit: if **compz** = **Nag_UpdateZ** or **Nag_InitZ**, **z** contains the unitary matrix of the required Schur vectors, unless **fail** $>$ 0.
z is not referenced if **compz** = **Nag_NotZ**.
- 11: **pdz** – Integer *Input*
On entry: the stride separating matrix row or column elements (depending on the value of **order**) in the array **z**.
Constraints:
 if **compz** = **Nag_UpdateZ** or **Nag_InitZ**, **pdz** \geq $\max(1, \mathbf{n})$;
 if **compz** = **Nag_NotZ**, **pdz** \geq 1.
- 12: **fail** – NagError * *Output*
 The NAG error parameter (see the Essential Introduction).

6 Error Indicators and Warnings

NE_INT

On entry, **n** = $\langle value \rangle$.
 Constraint: **n** \geq 0.

On entry, **pdh** = $\langle value \rangle$.
 Constraint: **pdh** $>$ 0.

On entry, **pdz** = $\langle value \rangle$.
 Constraint: **pdz** $>$ 0.

NE_INT_2

On entry, **pdh** = $\langle value \rangle$, **n** = $\langle value \rangle$.
 Constraint: **pdh** \geq $\max(1, \mathbf{n})$.

NE_INT_3

On entry, **n** = $\langle value \rangle$, **ilo** = $\langle value \rangle$, **ihi** = $\langle value \rangle$.
 Constraint: **ilo** \geq 1 and $\min(\mathbf{ilo}, \mathbf{n}) \leq \mathbf{ihi} \leq \mathbf{n}$.

NE_ENUM_INT_2

On entry, **compz** = $\langle value \rangle$, **n** = $\langle value \rangle$, **pdz** = $\langle value \rangle$.
 Constraint: if **compz** = **Nag_UpdateZ** or **Nag_InitZ**, **pdz** $\geq \max(1, \mathbf{n})$;
 if **compz** = **Nag_NotZ**, **pdz** ≥ 1 .

NE_CONVERGENCE

The algorithm has failed to find all the eigenvalues after a total of $30(\mathbf{ihi} - \mathbf{ilo} + 1)$ iterations.

NE_ALLOC_FAIL

Memory allocation failed.

NE_BAD_PARAM

On entry, parameter $\langle value \rangle$ had an illegal value.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

7 Accuracy

The computed Schur factorization is the exact factorization of a nearby matrix $H + E$, where

$$\|E\|_2 = O(\epsilon)\|H\|_2,$$

and ϵ is the *machine precision*.

If λ_i is an exact eigenvalue, and $\tilde{\lambda}_i$ is the corresponding computed value, then

$$|\tilde{\lambda}_i - \lambda_i| \leq \frac{c(n)\epsilon\|H\|_2}{s_i},$$

where $c(n)$ is a modestly increasing function of n , and s_i is the reciprocal condition number of λ_i . The condition numbers s_i may be computed by calling `nag_ztrsna` (f08qyc).

8 Further Comments

The total number of real floating-point operations depends on how rapidly the algorithm converges, but is typically about:

- $25n^3$ if only eigenvalues are computed;
- $35n^3$ if the Schur form is computed;
- $70n^3$ if the full Schur factorization is computed.

The real analogue of this function is `nag_dhseqr` (f08pec).

9 Example

To compute all the eigenvalues and the Schur factorization of the upper Hessenberg matrix H , where

$$H = \begin{pmatrix} -3.9700 - 5.0400i & -1.1318 - 2.5693i & -4.6027 - 0.1426i & -1.4249 + 1.7330i \\ -5.4797 + 0.0000i & 1.8585 - 1.5502i & 4.4145 - 0.7638i & -0.4805 - 1.1976i \\ 0.0000 + 0.0000i & 6.2673 + 0.0000i & -0.4504 - 0.0290i & -1.3467 + 1.6579i \\ 0.0000 + 0.0000i & 0.0000 + 0.0000i & -3.5000 + 0.0000i & 2.5619 - 3.3708i \end{pmatrix}.$$

See also `nag_zunghr` (f08ntc), which illustrates the use of this function to compute the Schur factorization of a general matrix.

9.1 Program Text

```

/* nag_zhseqr (f08psc) Example Program.
 *
 * Copyright 2001 Numerical Algorithms Group.
 *
 * Mark 7, 2001.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf08.h>
#include <nagx04.h>

int main(void)
{
    /* Scalars */
    Integer i, j, n, pdh, pdz, w_len;
    Integer exit_status=0;
    NagError fail;
    Nag_OrderType order;
    /* Arrays */
    Complex *h=0, *w=0, *z=0;

#ifdef NAG_COLUMN_MAJOR
#define H(I,J) h[(J-1)*pdh + I - 1]
    order = Nag_ColMajor;
#else
#define H(I,J) h[(I-1)*pdh + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);
    Vprintf("f08psc Example Program Results\n\n");

    /* Skip heading in data file */
    Vscanf("%*[\n] ");
    Vscanf("%ld%*[\n] ", &n);
#ifdef NAG_COLUMN_MAJOR
    pdh = n;
    pdz = n;
#else
    pdh = n;
    pdz = n;
#endif
    w_len = n;

    /* Allocate memory */
    if ( !(h = NAG_ALLOC(n * n, Complex)) ||
        !(w = NAG_ALLOC(w_len, Complex)) ||
        !(z = NAG_ALLOC(n * n, Complex)) )
    {
        Vprintf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

    /* Read H from data file */
    for (i = 1; i <= n; ++i)
    {
        for (j = 1; j <= n; ++j)
            Vscanf(" ( %lf , %lf )", &H(i,j).re, &H(i,j).im);
    }
    Vscanf("%*[\n] ");

    /* Calculate the eigenvalues and Schur factorization of H */
    f08psc(order, Nag_Schur, Nag_InitZ, n, 1, n, h, pdh,
          w, z, pdz, &fail);
    if (fail.code != NE_NOERROR)
    {

```

```

    Vprintf("Error from f08psc.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
Vprintf(" Eigenvalues\n");
for (i = 1; i <= n; ++i)
    Vprintf("(%7.4f,%7.4f) ", w[i-1].re, w[i-1].im);
Vprintf("\n\n");

/* Print Schur form */
x04dbc(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, n,
        h, pdh, Nag_BracketForm, "%7.4f", "Schur form",
        Nag_IntegerLabels, 0, Nag_IntegerLabels, 0, 80,
        0, 0, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from x04dbc.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
/* Print Schur vectors */
Vprintf("\n");
x04dbc(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, n,
        z, pdz, Nag_BracketForm, "%7.4f",
        "Schur vectors of H", Nag_IntegerLabels, 0,
        Nag_IntegerLabels, 0, 80, 0, 0, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from x04dbc.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
END:
if (h) NAG_FREE(h);
if (w) NAG_FREE(w);
if (z) NAG_FREE(z);

return exit_status;
}

```

9.2 Program Data

f08psc Example Program Data

```

4                                     :Value of N
(-3.9700,-5.0400) (-1.1318,-2.5693) (-4.6027,-0.1426) (-1.4249, 1.7330)
(-5.4797, 0.0000) ( 1.8585,-1.5502) ( 4.4145,-0.7638) (-0.4805,-1.1976)
( 0.0000, 0.0000) ( 6.2673, 0.0000) (-0.4504,-0.0290) (-1.3467, 1.6579)
( 0.0000, 0.0000) ( 0.0000, 0.0000) (-3.5000, 0.0000) ( 2.5619,-3.3708)
                                     :End of matrix H

```

9.3 Program Results

f08psc Example Program Results

Eigenvalues
(-6.0004,-6.9998) (-5.0000, 2.0060) (7.9982,-0.9964) (3.0023,-3.9998)

Schur form

	1	2	3	4
1	(-6.0004,-6.9998)	(-0.2080, 0.4719)	(-0.4829, 0.1768)	(0.1301, 0.9052)
2	(0.0000, 0.0000)	(-5.0000, 2.0060)	(-0.6653, 0.2814)	(0.0038, 0.2639)
3	(0.0000, 0.0000)	(0.0000, 0.0000)	(7.9982,-0.9964)	(0.2004, 1.0595)
4	(0.0000, 0.0000)	(0.0000, 0.0000)	(0.0000, 0.0000)	(3.0023,-3.9998)

Schur vectors of H

	1	2	3	4
1	(0.8457, 0.0000)	(0.1380, 0.3602)	(-0.2677,-0.1091)	(-0.2213,-0.0582)
2	(0.2824,-0.3304)	(-0.4612, 0.2075)	(0.6846, 0.0000)	(0.2927, 0.0320)
3	(0.0748, 0.2800)	(0.7239, 0.0000)	(0.5924,-0.0189)	(-0.0229, 0.2005)
4	(0.0670, 0.0860)	(0.2169, 0.1560)	(-0.2745, 0.1454)	(0.9057, 0.0000)